

Fri: HW by 5pm

Tues: Read 11.1.1, 11.1.2

### Potentials for a moving point charge

Suppose that a point charge with charge  $q$  moves along trajectory  $\vec{w}(t)$ . We can determine the potentials at point  $\vec{r}$  at time  $t$  as follows:

① Determine retarded time  $t_r$  by solving

$$c(t-t_r) = |\vec{r} - \vec{w}(t_r)|$$

② Determine retarded position by

$$\vec{r}_r = \vec{w}(t_r)$$

and retarded separation vector

$$\vec{s}_r = \vec{r} - \vec{r}_r$$

③ Calculate scalar potential

$$V(\vec{r}, t) = \frac{q}{4\pi\epsilon_0} \frac{c}{|\vec{s}_r| c - \vec{s}_r \cdot \vec{v}}$$

$$\text{where } \vec{v} = \frac{d\vec{w}}{dt}|_{t_r}$$

Liénard -  
Wiechert potentials

④ Calculate vector potential

$$\vec{A}(\vec{r}, t) = \frac{\vec{v}(t_r)}{c^2} V(\vec{r}, t)$$

## Fields produced by a moving point charge

The fields are given by a standard method.

$$\vec{E} = -\vec{\nabla} V - \frac{\partial \vec{A}}{\partial t}$$

$$\vec{B} = \vec{\nabla} \times \vec{A}$$

This entails differentiation. For the scalar potential, the derivatives are with respect to  $x, y, z$  and  $t$  and the crucial terms will be

differentiate  $\vec{r} \cdot \vec{c} - \vec{r} \cdot \vec{v} - \vec{v} \cdot \vec{v}$  and  $\vec{V}(tr)$

Now  $\vec{r} = \vec{r} - \vec{w}(tr)$  and so when differentiating we need to

differentiate explicitly  
w.r.t to  $x, y, z$

$\approx$  differentiate  $\vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$

differentiate implicitly  
with respect to  $x, y, z, t$

$\approx$  differentiate  $tr$  w.r.t  
 $x, y, z, t$

Differentiate implicitly in  
 $\vec{r}(tr)$

Since the variables all appear  
in  $tr$  via  $\vec{r}$  here

$$c(t-tr) = (\vec{r} - \vec{w}(tr))$$

The relevant derivatives appear as follows (Proofs later)

Lemma 1

$$\vec{\nabla} \cdot \vec{v}_r = \frac{-\vec{s}_r}{s_r c - \vec{v} \cdot \vec{s}_r}$$

Lemma 2

$$\vec{\nabla}(-\vec{s}_r \cdot \vec{v}) = \vec{v} + (\vec{s}_r \cdot \vec{a} - v^2) \vec{\nabla} \cdot \vec{v}_r$$

where the retarded acceleration is

$$\vec{a} = \left. \frac{d^2 \vec{w}}{dt^2} \right|_{tr}$$

Lemma 3

$$\frac{\partial \vec{v}_r}{\partial t} = \frac{\vec{s}_r c}{c \vec{s}_r - \vec{v} \cdot \vec{s}_r}$$

Lemma 4

$$\frac{\partial}{\partial t}(\vec{v} \cdot \vec{s}_r) = \frac{\partial \vec{v}_r}{\partial t} (\vec{s}_r \cdot \vec{a} - v^2)$$

$$\text{Lemma 1: } \vec{\nabla} \vec{t}_r = \frac{-\vec{s}_r}{s_r c - \vec{s}_r \cdot \vec{v}}$$

Proof: The retarded time depends implicitly on  $\vec{r}$ . Specifically

$$c(t-t_r) = s_r$$

$$\Rightarrow c(t-t_r) = (\vec{s}_r \cdot \vec{s}_r)^{1/2}$$

$$\Rightarrow \vec{\nabla}(c(t-t_r)) = \vec{\nabla}(\dots)^{1/2}$$

$$\Rightarrow -c \vec{\nabla} t_r = \frac{1}{2} \left[ \frac{1}{\vec{s}_r \cdot \vec{s}_r} \right]^{1/2} \vec{\nabla}(\vec{s}_r \cdot \vec{s}_r)$$

$$\Rightarrow -c \vec{\nabla} t_r = \frac{1}{2s_r} \left\{ \vec{s}_r \times (\vec{\nabla} \times \vec{s}_r) + \vec{s}_r \times (\vec{\nabla} \times \vec{s}_r) + (\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r + (\vec{s}_r \cdot \vec{\nabla})(\vec{s}_r) \right\}$$

$$\Rightarrow -c \vec{\nabla} t_r = \frac{1}{s_r} \left[ \vec{s}_r \times (\vec{\nabla} \times \vec{s}_r) + (\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r \right]$$

We will show:

$$\textcircled{A}: \vec{\nabla} \times \vec{s}_r = \vec{v} \times \vec{\nabla} t_r$$

$$\textcircled{B}: (\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r = \vec{s}_r - \vec{v} [\vec{s}_r \cdot \vec{\nabla}(t_r)]$$

First to prove  $\textcircled{A}$ :

$$\begin{aligned} \vec{\nabla} \times \vec{s}_r &= \vec{\nabla} \times (\vec{r} - \vec{w}(t_r)) \\ &= \cancel{\vec{\nabla} \times \vec{r}} - \vec{\nabla} \times \vec{w}(t_r) \\ &= -\vec{\nabla} \times \vec{w}(t_r) \end{aligned}$$

$$\text{But } \vec{\nabla} \times \vec{w} = \left( \frac{\partial w_y}{\partial x} - \frac{\partial w_x}{\partial y} \right) \hat{z} + \left( \frac{\partial w_z}{\partial y} - \frac{\partial w_y}{\partial z} \right) \hat{x} + \left( \frac{\partial w_x}{\partial z} - \frac{\partial w_z}{\partial x} \right) \hat{y}$$

$$\text{and } \frac{\partial w_y}{\partial x} = \frac{\partial w_y}{\partial t_r} \frac{\partial t_r}{\partial x} \\ = \left. \frac{dw_y}{dt} \right|_{t_r} \frac{\partial t_r}{\partial x} \quad \text{etc., ...}$$

gives:

$$\begin{aligned} \vec{\nabla} \times \vec{w} &= \left( \frac{dw_y}{dt} \frac{\partial t_r}{\partial x} - \frac{dw_x}{dt} \frac{\partial t_r}{\partial y} \right) \hat{z} + \dots \\ &= \left[ \left. \frac{dw_y}{dt} (\vec{\nabla} t_r)_x - \frac{dw_x}{dt} (\vec{\nabla} t_r)_y \right] \hat{z} + \dots \\ &= \vec{\nabla}(t_r) \times \frac{d\vec{w}}{dt} \Big|_{t_r} \end{aligned}$$

$$\Rightarrow \vec{\nabla} \times \vec{s}_r = -\vec{\nabla}(t_r) \times \vec{v} = \vec{v} \times \vec{\nabla}(t_r)$$

and this proves A.

$$\text{To prove (3): } (\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r = \vec{s}_r \cdot \vec{\nabla} (\vec{v} - \vec{w}(t_r)).$$

Then for any vector  $\vec{a}$  it is easily shown that  $(\vec{a} \cdot \vec{\nabla})^2 = \vec{a}$ .

Thus

$$(\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r = \vec{s}_r - \vec{s}_r \cdot \vec{\nabla} (\vec{w}(t_r))$$

Now

$$\begin{aligned} \vec{b} \cdot \vec{\nabla} (\vec{w}(t_r)) &= b_x \frac{\partial}{\partial x} \vec{w}(t_r) + b_y \frac{\partial}{\partial y} \vec{w}(t_r) + b_z \frac{\partial}{\partial z} \vec{w}(t_r) \\ &= b_x \left. \frac{d\vec{w}}{dt} \right|_{t_r} \frac{\partial t_r}{\partial x} + b_y \left. \frac{d\vec{w}}{dt} \right|_{t_r} \frac{\partial t_r}{\partial y} + \dots \\ &= \frac{d\vec{w}}{dt} \left[ \vec{b} \cdot \vec{\nabla}(t_r) \right]. \end{aligned}$$

Thus.

$$\begin{aligned} (\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r &= \vec{s}_r - \frac{d\vec{s}}{dt} \Big|_{tr} - \vec{s}_r \cdot \vec{\nabla}(tr) \\ &= \vec{s}_r - \vec{v} (\vec{s}_r \cdot \vec{\nabla}(b_r)) \end{aligned}$$

which proves B. So

$$\begin{aligned} -c \vec{\nabla}(b_r) &= \frac{1}{s_r} \left\{ \vec{s}_r \times [\vec{v} \times \vec{\nabla}(tr)] + (\vec{s}_r \cdot \vec{\nabla}) \vec{s}_r \right\} \\ &= \frac{1}{s_r} \left\{ \vec{v} (\vec{s}_r \cdot \vec{\nabla}(tr)) - \vec{\nabla}(b_r) (\vec{v} \cdot \vec{s}_r) + \vec{s}_r - \vec{v} (\vec{s}_r \cdot \vec{\nabla}(b_r)) \right\} \\ \Rightarrow c \vec{\nabla}(tr) &= \frac{1}{s_r} \left\{ \vec{\nabla}(b_r) (\vec{v} \cdot \vec{s}_r) - \vec{s}_r \right\} \\ \Rightarrow \vec{\nabla}(b_r) [s_r c - \vec{v} \cdot \vec{s}_r] &= -\vec{s}_r \\ \Rightarrow \vec{\nabla}(tr) &= \frac{-\vec{s}_r}{s_r c - \vec{v} \cdot \vec{s}_r} \end{aligned}$$

$$\underline{\text{Lemma 2}} \quad \vec{\nabla}(\vec{r}_r \cdot \vec{v}) = \vec{v} + (\vec{r}_r \cdot \vec{a} - v^2) \vec{\nabla}(t_r)$$

where

$$\vec{a} = \frac{d\vec{w}}{dt^2} \Big|_{t_r}$$

$$\begin{aligned} \underline{\text{Proof.}} \quad \vec{\nabla}(\vec{r}_r \cdot \vec{v}) &= \vec{r}_r \times (\vec{\nabla} \times \vec{v}) + \vec{v} \times (\vec{\nabla} \times \vec{r}_r) \\ &\stackrel{\uparrow}{\text{evaluated at } t_r} + (\vec{r}_r \cdot \vec{\nabla}) \vec{v} + (\vec{v} \cdot \vec{\nabla}) \cdot \vec{r}_r \end{aligned}$$

We saw in lemma 1 that,

$$\vec{\nabla} \times \vec{r}_r = \vec{v} \times \vec{\nabla}(t_r)$$

$$\begin{aligned} \text{Then } \vec{\nabla} \times \vec{v} &= \left( \frac{\partial v_y}{\partial z} - \frac{\partial v_z}{\partial y} \right) \hat{x} + \dots \\ &= \left( \frac{dv_y}{dt} \Big|_{t_r} \frac{\partial t_r}{\partial z} - \frac{dv_z}{dt} \Big|_{t_r} \frac{\partial t_r}{\partial y} \right) \hat{x} + \dots \\ &= [a_y (\vec{\nabla}(t_r))_z - a_z (\vec{\nabla}(t_r))_y] \hat{x} + \dots \\ &= \vec{\nabla}(t_r) \times \vec{a} \end{aligned}$$

$$\begin{aligned} \text{So } \vec{\nabla}(\vec{r}_r \cdot \vec{v}) &= \vec{r}_r \times [\vec{\nabla}(t_r) \times \vec{a}] + \vec{v} \times [\vec{v} \times \vec{\nabla}(t_r)] \\ &\quad + (\vec{r}_r \cdot \vec{\nabla}) \vec{v} + (\vec{v} \cdot \vec{\nabla}) \cdot \vec{r}_r \end{aligned}$$

$$\begin{aligned} \text{Then } (\vec{r}_r \cdot \vec{\nabla}) \vec{v} &= r_x \frac{\partial}{\partial x} \vec{v} + r_y \frac{\partial}{\partial y} \vec{v} + \dots \\ &= r_x \frac{d\vec{v}}{dt} \Big|_{t_r} \frac{dt_r}{dx} + \dots \\ &= [\vec{r} \cdot \vec{\nabla}(t_r)] \vec{a} \end{aligned}$$

Also:  $(\vec{V} \cdot \vec{\nabla}) \vec{s}_r = v_x \frac{\partial}{\partial x} \vec{s}_r + v_y \frac{\partial}{\partial y} \vec{s}_r + \dots$  and  $\vec{s}_r = \vec{r} - \vec{w}(t_r)$

$$= v_x \hat{x} - [\vec{V} \cdot \vec{\nabla}(b_r)] \hat{v}_x \hat{x} + \dots$$

$$= \vec{v} - [\vec{V} \cdot \vec{\nabla}(b_r)] \vec{v}$$

Thus:  $\vec{\nabla}(\vec{s}_r \cdot \vec{v}) = [\vec{\nabla}(t_r)] \vec{s}_r \cdot \vec{a} - \vec{a} [\vec{s}_r \cdot \vec{\nabla}(b_r)]$

$$+ \vec{v} [\vec{V} \cdot \vec{\nabla}(b_r)] - \vec{\nabla}(t_r) v^2$$

$$+ \vec{a} [\vec{s}_r \cdot \vec{\nabla}(b_r)] + \vec{v} - \vec{v} [\vec{V} \cdot \vec{\nabla}(b_r)]$$

$$= \vec{v} + \vec{\nabla}(t_r) [\vec{s}_r \cdot \vec{a} - v^2]$$

This proves the result. □

Lemma 3

$$C(t-t_r) = |\vec{r} - \vec{w}(t_r)|$$

$$\Rightarrow C^2(t-t_r)^2 = |\vec{r}|^2 + w^2(t_r) - 2\vec{r} \cdot \vec{w}(t_r)$$

Differentiate w.r.t.  $t \Rightarrow C^2(t-t_r) \left[ 1 - \frac{\partial t_r}{\partial t} \right]$

$$= 2w \frac{dw}{dt} \Big|_{t_r} \frac{\partial t_r}{\partial t} - |\vec{r}| \cdot \frac{d\vec{r}}{dt} \Big|_{t_r} \frac{\partial t_r}{\partial t}$$

$$\Rightarrow C^2(t-t_r) = \frac{\partial t_r}{\partial t} \left[ C^2(t-t_r) + \vec{w} \cdot \vec{v} - \vec{r} \cdot \vec{v} \right]$$

$$\Rightarrow C \dot{s}_{\vec{r}} = \frac{\partial t_r}{\partial t} \left[ C^2(t-t_r) - \vec{v} \cdot \vec{s}_{\vec{r}} \right]$$

$$\Rightarrow \frac{\partial t_r}{\partial t} = \frac{C \dot{s}_{\vec{r}}}{C \dot{s}_{\vec{r}} - \vec{v} \cdot \vec{s}_{\vec{r}}} \quad \square$$

Lemma 4

$$\frac{\partial}{\partial t} (\vec{v} \cdot \vec{s}_{\vec{r}}) = \underbrace{\frac{\partial \vec{v}}{\partial t} \cdot \vec{s}_{\vec{r}}}_{\vec{a}} + \vec{v} \cdot \frac{\partial \vec{s}_{\vec{r}}}{\partial t}$$

$$\underbrace{\frac{\partial \vec{v}}{\partial t_r} \frac{\partial t_r}{\partial t}}_{\vec{a}}$$

$$= \vec{a} \cdot \vec{s}_{\vec{r}} \frac{\partial t}{\partial t_r} + \vec{v} \left( -\frac{\partial \vec{w}}{\partial t} \right)$$

$$= \left( \vec{a} \cdot \vec{s}_{\vec{r}} - \vec{v} \cdot \vec{v} \right) \frac{\partial t}{\partial t_r}$$

$$= \left( \vec{s}_{\vec{r}} \cdot \vec{a} - v^2 \right) \frac{\partial t}{\partial t_r} \quad \square$$

## Electric field

There are two contributions to  $\vec{E}$ :

a)  $-\vec{\nabla} V$

b)  $-\frac{\partial \vec{A}}{\partial t}$

Consider the scalar potential

$$\vec{\nabla} V = \frac{q_c}{4\pi\epsilon_0} \vec{\nabla} (s_r c - \vec{v} \cdot \vec{s}_r)^{-1}$$

$$= -\frac{q_c}{4\pi\epsilon_0} (s_r c - \vec{v} \cdot \vec{s}_r)^{-2} [c \vec{\nabla} s_r - \vec{\nabla} (\vec{v} \cdot \vec{s}_r)]$$

Now  $s_r = c(t-t_r) \Rightarrow \vec{\nabla} s_r = -c \vec{\nabla} t_r$  and

$$\vec{\nabla} (\vec{v} \cdot \vec{s}_r) = \vec{v} + (\vec{s}_r \cdot \vec{a} - v^2) \vec{\nabla} t_r$$

give

$$\vec{\nabla} V = -\frac{q_c}{4\pi\epsilon_0} \frac{1}{(s_r c - \vec{v} \cdot \vec{s}_r)} [ (v^2 - c^2) \vec{\nabla} t_r - \vec{v} - \vec{s}_r \cdot \vec{a} \vec{\nabla} t_r ]$$

Then by Lemma 1

$$\vec{\nabla} V = -\frac{q_c}{4\pi\epsilon_0} \frac{1}{(s_r c - \vec{v} \cdot \vec{s}_r)^2} \left[ \frac{c^2 - v^2 + \vec{s}_r \cdot \vec{a}}{s_r c - \vec{v} \cdot \vec{s}_r} \vec{s}_r - \vec{v} \right]$$

$$= -\frac{q_c}{4\pi\epsilon_0} \frac{1}{(s_r c - \vec{v} \cdot \vec{s}_r)} \left[ \vec{s}_r (c^2 - v^2 + \vec{s}_r \cdot \vec{a}) - \vec{v} (s_r c - \vec{v} \cdot \vec{s}_r) \right]$$

Now consider the vector potential.

$$\frac{\partial \vec{A}}{\partial t} = \frac{\mu_0 q_c}{4\pi} \frac{\partial}{\partial t} \frac{\vec{v}(t_r)}{s_r c - \vec{v} \cdot \vec{s}_r} = \frac{\mu_0 q_c}{4\pi} \frac{\frac{\partial \vec{v}(t_r)}{\partial t} (s_r c - \vec{v} \cdot \vec{s}_r) - \vec{v}(t_r) \frac{\partial}{\partial t} (s_r c - \vec{v} \cdot \vec{s}_r)}{(s_r c - \vec{v} \cdot \vec{s}_r)^2}$$

Then

$$\frac{\partial \vec{v}}{\partial t} = \frac{\partial \vec{v}}{\partial t_r} \frac{\partial t_r}{\partial t} = \vec{a} \frac{\partial t_r}{\partial t}$$

evaluated at  $t_r = \frac{dv}{dt} \Big|_{t_r}$

and

$$\frac{\partial (\vec{s}_r c)}{\partial t} = c \frac{\partial \vec{s}_r}{\partial t} = c \frac{\partial}{\partial t} c(t - t_r) = c^2 \left[ 1 - \frac{\partial t_r}{\partial t} \right]$$

$$\frac{\partial}{\partial t} (\vec{s}_r \cdot \vec{v}) = \frac{\partial t_r}{\partial t} (\vec{s}_r \cdot \vec{a} - v^2)$$

Thus

$$\begin{aligned} \frac{\partial \vec{A}}{\partial t} &= \frac{\mu_0 q c}{4\pi} \vec{a} \underbrace{\left[ \vec{s}_r c - \vec{s}_r \cdot \vec{v} \right] \frac{\partial t_r}{\partial t} - \vec{v} \left[ c^2 \left( 1 - \frac{\partial t_r}{\partial t} \right) - \frac{\partial t_r}{\partial t} (\vec{s}_r \cdot \vec{a} - v^2) \right]}_{(\vec{s}_r c - \vec{s}_r \cdot \vec{v})^2} \\ &= \frac{\mu_0 q c}{4\pi} \frac{1}{(\vec{s}_r c - \vec{s}_r \cdot \vec{v})^2} \left\{ (\vec{s}_r c - \vec{s}_r \cdot \vec{v}) \vec{a} + \vec{v} c^2 + (\vec{s}_r \cdot \vec{a}) \vec{v} + \vec{v} v^2 \right\} \frac{\partial t_r}{\partial t} - c^2 \vec{v} \} \\ &= \frac{\mu_0 q c}{4\pi} \frac{1}{(\vec{s}_r c - \vec{s}_r \cdot \vec{v})^2} \left\{ \left( \frac{\vec{s}_r c}{\vec{s}_r c - \vec{s}_r \cdot \vec{v}} \right) \left[ (\vec{s}_r c - \vec{s}_r \cdot \vec{v}) \vec{a} + \vec{v} (c^2 - v^2) + \vec{v} (\vec{s}_r \cdot \vec{a}) \right] - c^2 \vec{v} \right\} \\ &= \frac{\mu_0 q c}{4\pi} \frac{1}{(\vec{s}_r c - \vec{s}_r \cdot \vec{v})^3} \left\{ \vec{s}_r c \left[ (\vec{s}_r c - \vec{s}_r \cdot \vec{v}) \vec{a} + \vec{v} (c^2 - v^2) + \vec{v} (\vec{s}_r \cdot \vec{a}) \right] - c^2 \vec{v} (\vec{s}_r c - \vec{s}_r \cdot \vec{v}) \right\} \\ &= \frac{q c}{4\pi \epsilon_0 c} \frac{1}{(\dots)^3} \left\{ (\vec{s}_r c - \vec{s}_r \cdot \vec{v}) (\vec{s}_r c \vec{a} - c^2 \vec{v}) + \vec{s}_r c \vec{v} (c^2 - v^2 + \vec{s}_r \cdot \vec{a}) \right\} \\ &= \frac{q c}{4\pi \epsilon_0 c} \frac{1}{(\dots)^3} \left\{ (\vec{s}_r c - \vec{s}_r \cdot \vec{v}) \left( \frac{\vec{s}_r \vec{a}}{c} - \vec{v} \right) + \frac{\vec{s}_r}{c} \vec{v} (c^2 - v^2 + \vec{s}_r \cdot \vec{a}) \right\} \\ \Rightarrow \vec{\nabla} V + \frac{\partial \vec{A}}{\partial t} &= \frac{q c}{4\pi \epsilon_0 c} \frac{1}{(\dots)^3} \left[ -\vec{s}_r (c^2 - v^2 + \vec{s}_r \cdot \vec{a}) + (\vec{s}_r c - \vec{v} \cdot \vec{s}_r) \frac{\vec{s}_r \vec{a}}{c} + \frac{\vec{s}_r}{c} \vec{v} (c^2 - v^2 + \vec{s}_r \cdot \vec{a}) \right] \\ &= \frac{q c}{4\pi \epsilon_0 c} \frac{1}{(\dots)^3} \left\{ (\vec{s}_r c - \vec{v} \cdot \vec{s}_r) \frac{\vec{s}_r \vec{a}}{c} + (c^2 - v^2 + \vec{s}_r \cdot \vec{a}) \left[ \frac{\vec{s}_r \vec{v}}{c} - \vec{s}_r \right] \right\} \end{aligned}$$

$$\Rightarrow \vec{\nabla} V + \frac{d\vec{A}}{dt} = \frac{q}{4\pi\epsilon_0 c^3} \left\{ (\vec{s}_r c - \vec{v} \cdot \vec{s}_r) \cdot \vec{s}_r \vec{a} + (c^2 v^2 + \vec{s}_r \cdot \vec{a}) (\vec{s}_r \vec{v} - c \vec{s}_r) \right\}$$

$$\Rightarrow \vec{E} = -\frac{q}{4\pi\epsilon_0} \frac{1}{(\vec{s}_r c - \vec{v} \cdot \vec{s}_r)^3} \left\{ \vec{s}_r \vec{a} (\vec{s}_r c - \vec{v} \cdot \vec{s}_r) + (c^2 v^2 + \vec{s}_r \cdot \vec{a}) (\vec{s}_r \vec{v} - c \vec{s}_r) \right\}$$

Now define

$$\boxed{\vec{u} := c \hat{s}_r - \vec{v}}$$

Then

$$E = -\frac{q}{4\pi\epsilon_0} \frac{1}{(\vec{u} \cdot \vec{s}_r)^3} \left\{ \vec{s}_r \vec{a} (\vec{u} \cdot \vec{s}_r) - (c^2 v^2 + \vec{s}_r \cdot \vec{a}) \vec{s}_r \vec{u} \right\}$$

$$= -\frac{q}{4\pi\epsilon_0} \frac{1}{(\vec{u} \cdot \vec{s}_r)^3} \left\{ (c^2 v^2) \vec{s}_r \vec{u} + \vec{s}_r [\vec{u} (\vec{u} \cdot \vec{s}_r) - \vec{s}_r \vec{u} (\vec{s}_r \cdot \vec{a})] \right\}$$

$$= \frac{q}{4\pi\epsilon_0} \frac{\vec{s}_r}{(\vec{u} \cdot \vec{s}_r)^3} \left\{ (c^2 v^2) \vec{u} - \vec{s}_r \times (\vec{a} \times \vec{u}) \right\}.$$

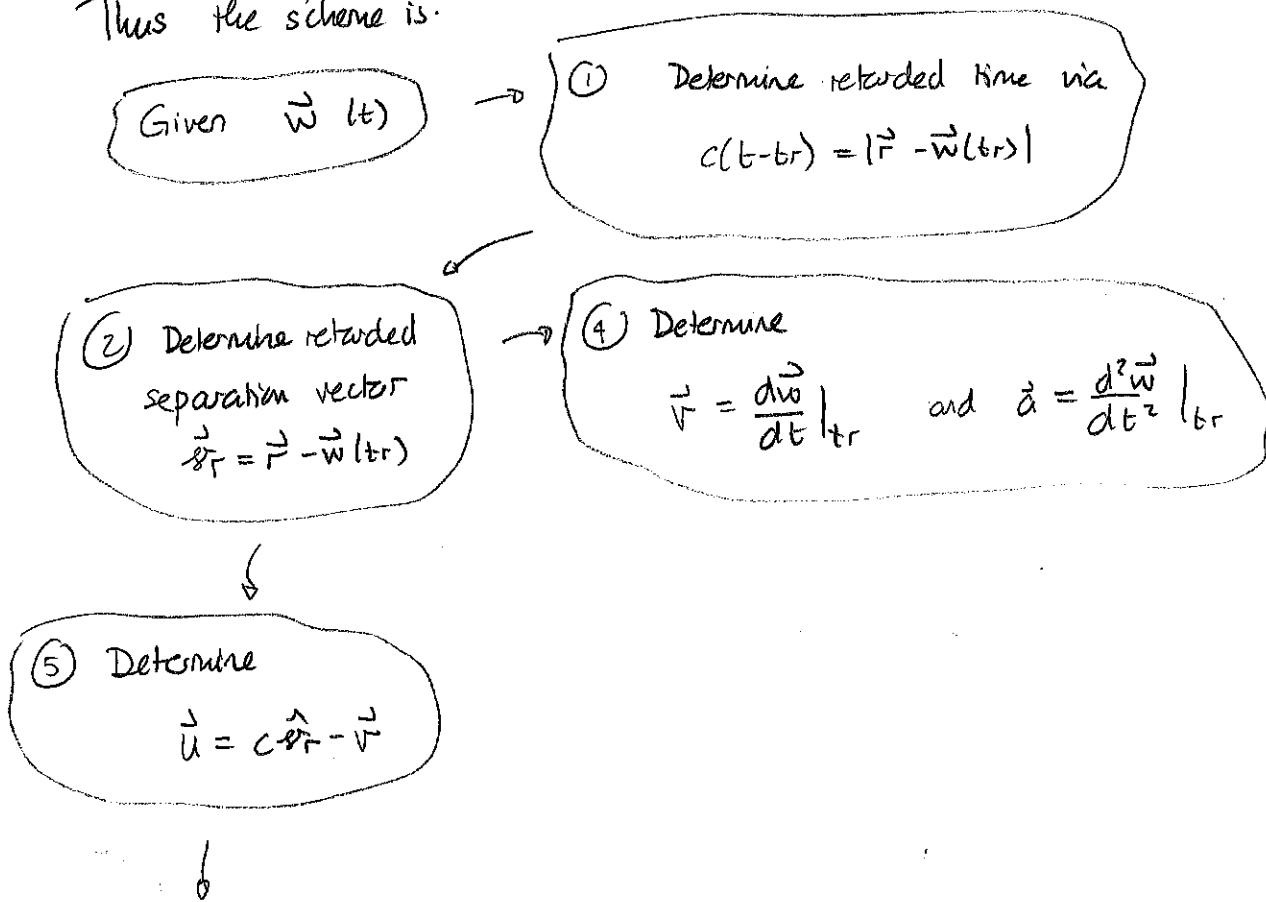
so

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{s}_r}{(\vec{u} \cdot \vec{s}_r)^3} \left\{ (c^2 v^2) \vec{u} + \vec{s}_r \times (\vec{u} \times \vec{a}) \right\}.$$

A similar vector calculus calculation gives

$$\vec{B} = \frac{1}{c} (\hat{s}_r \times \vec{E})$$

Thus the scheme is.



The fields are

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\hat{\vec{r}}_r}{(\hat{\vec{r}}_r \cdot \vec{u})^3} \left[ (c^2 - v^2) \vec{u} + \hat{\vec{r}}_r \times (\vec{u} \times \vec{a}) \right]$$

$$\vec{B} = \frac{1}{c} \hat{\vec{r}}_r \times \vec{E}$$

## 1 Fields produced by a charge moving with constant velocity

Consider a charged particle moving with constant velocity. Thus

$$\mathbf{w}(t) = \mathbf{v} t$$

where  $\mathbf{v}$  is the velocity.

a) Show that

$$\mathbf{u} = \frac{\mathbf{r} - \mathbf{v} t}{t - t_r}.$$

b) Determine an expression for the electric field.

c) Determine an expression for the magnetic field.

d) Let  $\mathbf{R} = \mathbf{r} - \mathbf{v} t$ . Provide a geometric interpretation of this.

e) Express the electric field in terms of  $\mathbf{R}$ . Note that it can be shown that

$$1 - \frac{\mathbf{r} \cdot \mathbf{v}}{c} = \frac{R}{c} \sqrt{1 - \frac{v^2}{c^2} \sin^2 \theta}$$

where  $\theta$  is the angle between  $\mathbf{R}$  and  $\mathbf{v}$ .

f) Show that the magnitude of the Poynting vector scales as  $1/R^4$ . If you were to consider the energy that flows out of a very large sphere centered at the origin, what would this imply?

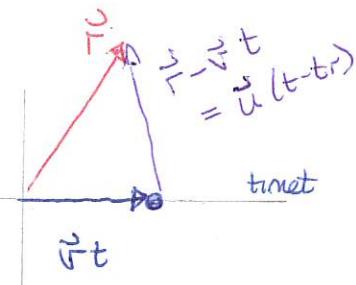
Answer a)



$$\vec{u} = c \hat{s}_r - \vec{v} = \frac{c}{s_r} \vec{r}_r - \vec{v}$$

$$\vec{r}_r = \vec{r} - \vec{w}(t_r) = \vec{r} - \vec{v} t_r$$

$$\Rightarrow \vec{u} = \frac{c}{s_r} (\vec{r} - \vec{v} t_r) - \vec{v}$$



$$\text{But } s_r = c(t - t_r)$$

$$\Rightarrow \vec{u} = \frac{\vec{r} - \vec{v} t_r}{t - t_r} - \vec{v} = \frac{\vec{r} - \vec{v} t_r - \vec{v}(t - t_r)}{t - t_r}$$

$$\Rightarrow \vec{u} = \frac{\vec{r} - \vec{v} t}{t - t_r}$$

b) Here  $\vec{a} = 0$

$$\vec{E} = \frac{q}{4\pi\epsilon_0} \frac{\vec{s}_r}{(\vec{u} \cdot \vec{s}_r)^3} (c^2 - v^2) \vec{u}$$

Then  $\vec{s}_r = c(t - br)$

$$\Rightarrow \vec{E} = \frac{q}{4\pi\epsilon_0} \frac{c(c^2 - v^2)}{(\vec{u} \cdot \vec{s}_r)^3} \underbrace{(\vec{t} - \vec{t}_r)}_{\vec{r} - \vec{v}t} \vec{u}$$

$$= \frac{q}{4\pi\epsilon_0} \frac{c(c^2 - v^2)}{(\vec{u} \cdot \vec{s}_r)^3} (\vec{r} - \vec{v}t)$$

$$\begin{aligned} \text{Then } \vec{u} \cdot \vec{s}_r &= (c\hat{s}_r - \vec{v}) \cdot \vec{s}_r \\ &= (c\hat{s}_r - \vec{v} \cdot \hat{s}_r) = c\hat{s}_r(1 - \vec{v} \cdot \hat{s}_r/c) \end{aligned}$$

$$\Rightarrow \vec{E} = \frac{q}{4\pi\epsilon_0} \frac{c(c^2 - v^2)}{c^3 \hat{s}_r^3 (1 - \vec{v} \cdot \hat{s}_r/c)^3} (\vec{r} - \vec{v}t)$$

$$= \frac{q}{4\pi\epsilon_0} \left(1 - \frac{v^2}{c^2}\right) \frac{1}{\hat{s}_r^3} \frac{1}{(1 - \hat{s}_r \cdot \vec{v}/c)^3} (\vec{r} - \vec{v}t)$$

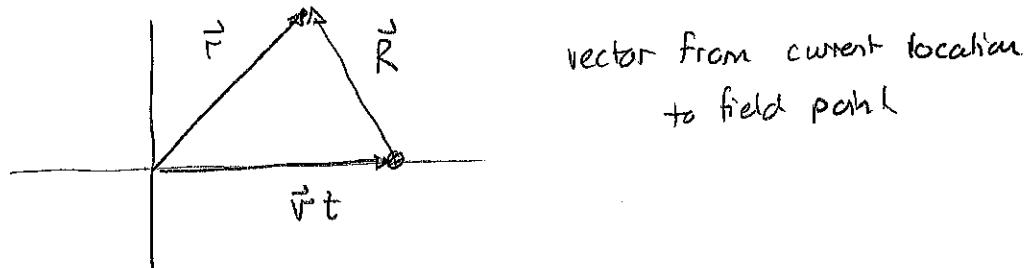
$$c) \vec{B} = \frac{1}{c} \hat{s}_r \times \vec{E} = \frac{1}{c} \frac{1}{\hat{s}_r} \hat{s}_r \times \vec{E}$$

$$\begin{aligned} \text{Then } \vec{s}_r &= \vec{r} - \vec{v}t_r \quad \text{and} \quad \vec{s}_r \times (\vec{r} - \vec{v}t) \\ &= (\vec{r} - \vec{v}t_r) \times (\vec{r} - \vec{v}t) \\ &= \vec{v} \times \vec{r} (t - t_r) \\ &= \vec{v} \times \vec{r} (+\vec{s}_r/c) \end{aligned}$$

Thus

$$\vec{B} = \frac{q}{4\pi G_0} \frac{1}{c^2} \left(1 - \frac{v^2}{c^2}\right) \frac{1}{r_r^3} \frac{1}{(1 - \hat{r} \cdot \hat{v}/c)^3} \hat{v} \times \hat{r}$$

d)



vector from current location  
to field path

$$e) \quad \vec{E} = \frac{q}{4\pi G_0} \left(1 - \frac{v^2}{c^2}\right) \frac{1}{r_r^3} \frac{\hat{R}}{R^3 / r_r^3 (1 - \frac{v^2}{c^2} \sin^2 \theta)^{3/2}}$$

$$\boxed{\vec{E} = \frac{q}{4\pi G_0} \frac{1}{R^2} \frac{(1 - \frac{v^2}{c^2})}{(1 - \frac{v^2}{c^2} \sin^2 \theta)^{3/2}} \hat{R}}$$

$$f) \quad \vec{B} = \frac{q}{4\pi G_0} \frac{1}{c^2} \left(1 - \frac{v^2}{c^2}\right) \frac{1}{R^3} \frac{1}{(1 - \frac{v^2}{c^2} \sin^2 \theta)^{3/2}} \hat{v} \times \hat{r}$$

$$\text{Then } \hat{v} \times \hat{r} = \hat{v} \times (\hat{R} - \hat{v} t) = \hat{v} \times \hat{R}$$

$$\Rightarrow \vec{B} = \frac{q}{4\pi G_0} \frac{1}{c^2} \left(1 - \frac{v^2}{c^2}\right) \frac{1}{R^3} \frac{1}{(1 - \frac{v^2}{c^2} \sin^2 \theta)^{3/2}} \hat{v} \times \hat{R}$$

$$\boxed{\vec{B} = \frac{1}{c^2} \frac{q}{4\pi G_0} \frac{1}{R^2} \left(1 - \frac{v^2}{c^2}\right) \frac{1}{(1 - \frac{v^2}{c^2} \sin^2 \theta)^{3/2}} \hat{v} \times \hat{R}}$$

$$\text{Note that } \vec{B} = \frac{1}{c^2} \hat{v} \times \vec{E}$$

Then

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B} \quad \text{and} \quad \frac{1}{c^2} \left( \frac{\alpha}{4\pi\epsilon_0} \right)^2 \frac{1}{R^4} \dots$$

For a sphere of radius  $r$  centered at the origin, energy flow is

$$\oint \vec{S} \cdot d\vec{a} \quad \left. \begin{array}{l} \text{surface} \\ \frac{1}{R^4} \approx r^2 \end{array} \right\} \text{the integral} \approx \frac{1}{r^2}$$

For very large  $r$  this is approximately zero

Note that the fields appear as

