

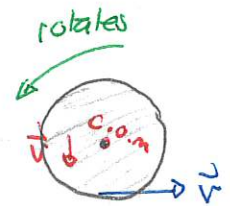
Thurs: Seminar 12:30
 Wubben 203

Fri: HW 5pm

Ex 390, 394, 395, 396, 398, 399, 401, 402

Rotational Energy

Consider a solid rotating object such as a pulley. Even though the center-of-mass is fixed, there must be some kinetic energy present as a result of the rotating mass. We cannot just express the kinetic energy as $\frac{1}{2}mv^2$ since there is a continuous range of velocities in the object. A general rule is:



Consider an object that rotates about some axis. The object has rotational kinetic energy

$$K_{rot} = \frac{1}{2} I \omega^2$$

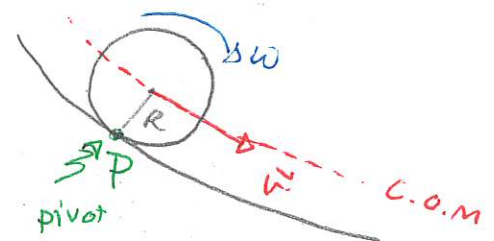
where I = moment of inertia about the rotation axis
 ω = angular velocity about the rotation axis.

For a proof see section 12.3.

Rotational and translational energies.

We now consider objects that simultaneously undergo translational and rotational motion. Let

- * \vec{v} = velocity of the center-of-mass
- * ω = angular velocity about the pivot P



Then one can show that

If the net work done by non-conservative forces is zero, then the total energy

$$E = K_{\text{trans}} + K_{\text{rot}} + U_{\text{grav}} + U_{\text{spring}} + \dots$$

stays constant. Here

$$K_{\text{rot}} = \frac{1}{2} I \omega^2 \quad \text{where } I = \text{moment of inertia about c.o.m.}$$

$$K_{\text{trans}} = \frac{1}{2} M V^2$$

Rolling without slipping

A special case of this motion is where the object rolls without slipping. Then the speed of the center of mass satisfies

$$V = \omega R$$

and this can be used to eliminate ω from the energy expression. So

$$K_{\text{trans}} + K_{\text{rot}} = \frac{1}{2} M V^2 + \frac{1}{2} I \omega^2$$

$$\omega = V/R$$

$$K_{\text{trans}} + K_{\text{rot}} = \frac{1}{2} M V^2 + \frac{1}{2} I \frac{V^2}{R^2}$$

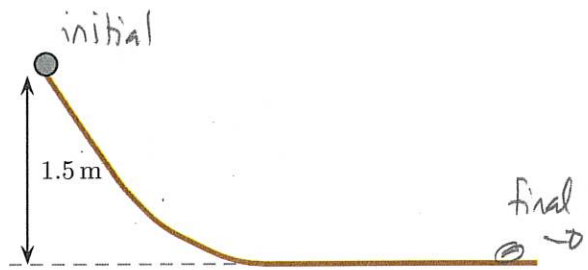
Quiz 1 30% - 60% \approx 30% ~

The energy conservation rule emerges by applying Newton's 2nd and 3rd Laws to the constituents of the rotating objects and finally translating into rotational motion terms.

~~Quiz 2~~

410 Rolling cylinder

A cylinder with mass M and radius R is released from rest at the top of a track with height 1.5 m. It rolls without slipping. Determine the speed of the cylinder at the bottom of the track. (131F2024)



$$E_f = E_i$$

$$K_{trans f} + K_{rot f} + U_{g f} =$$

$$K_{trans i} + K_{rot i} + U_{g i}$$

$$y_i = 1.5 \text{ m}$$

$$v_i = 0 \text{ m/s}$$

$$\omega_i = 0 \text{ rad/s}$$

$$y_f = 0 \text{ m}$$

$$v_f = ?$$

$$\omega_f = ?$$

$$\frac{1}{2} M v_f^2 + \frac{1}{2} I \omega_f^2 + M g y_f = \frac{1}{2} M v_i^2 + \frac{1}{2} I \omega_i^2 + M g y_i$$

Now $I = \frac{1}{2} M R^2$

$$\Rightarrow \frac{1}{2} M v_f^2 + \frac{1}{4} M R^2 \omega_f^2 = M g y_i$$

No-slip $\Rightarrow \omega_f = v_f / R$ and thus

$$\frac{1}{2} v_f^2 + \frac{1}{4} v_f^2 = g y_i \quad \Rightarrow \quad \frac{3}{4} v_f^2 = g y_i$$

$$\Rightarrow v_f = \sqrt{\frac{4 g y_i}{3}} = \sqrt{\frac{4 \times 9.8 \text{ m/s}^2 \times 1.5 \text{ m}}{3}}$$

$$= 4.4 \text{ m/s}$$

Note that if the ball slid without rolling

$$\frac{1}{2} v_f^2 = g y_i \Rightarrow v_f = \sqrt{2 g y_i}$$

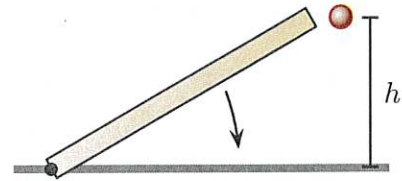
which is larger than the rolling case

Quiz 2 very few.

Quiz 3

405 Toppling rod versus freely falling ball, 1

A rigid rod with uniformly distributed mass M and length L can pivot about a frictionless axle in a horizontal surface. The rod is held at rest with one end height h above the surface. A ball with mass m is also held at rest alongside the tip of the rod. Both are released at the same time. (131F2024)



- Determine the speed of the ball just before it hits the horizontal surface.
- Determine the speed of the tip of the rod just before it hits the horizontal surface.
- Which hits first?

a) $E_f = E_i \Rightarrow K_f + U_{gf} = K_i + U_{gi}$

$$\Rightarrow \frac{1}{2} m v_f^2 + \cancel{mgy_f} = \cancel{\frac{1}{2} m v_i^2} + Mgy_i \Rightarrow v_f = \sqrt{2gh}$$

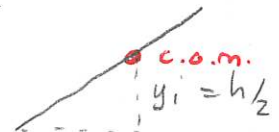
b) $E_f = E_i$

$$\cancel{K_{rotf}} + \cancel{K_{transf}} + \cancel{U_{gf}} = \cancel{K_{roti}} + \cancel{K_{transi}} + U_{gi}$$

The rotational kinetic energy is about the pivot, translational is at the pivot
 $\Rightarrow K_{trans} = 0$

$$\frac{1}{2} I_{rod} \omega_f^2 = Mgh/2$$

left end



$$\Rightarrow \frac{1}{2} \cdot \frac{1}{3} ML^2 \omega_f^2 = \frac{1}{2} Mgh$$

$$\Rightarrow \omega_f^2 L^2 = 3gh$$

But $\omega_f L = v_f \equiv$ speed of tip

$$\Rightarrow v_f = \sqrt{3gh}$$

DEMO: U Iowa Falling Chimney

DEMO: YouTube video