

Tues: Warm Up 14

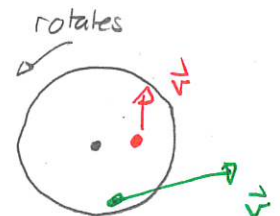
Thurs: Discussion/quiz

Ex: 316, 317, 318, 322, 323, 327

### Rotational energy

Consider a uniform disk that rotates about its center.

There will clearly be a kinetic energy associated with this, since there is moving mass. How can we account for this?



Quiz 1 30% - 80%  $\approx$  10% - 20%

With such rotating objects there is a multitude of velocities and the kinetic energy cannot be expressed as some mass  $\times v^2$ . However, a general rule is:

Consider an object that rotates about some axis. This object has rotational kinetic energy:

$$K_{rot} = \frac{1}{2} I \omega^2$$

where  $I$  = moment of inertia about the axis

$\omega$  = angular velocity " " axis

Proof. Consider any <sup>flat</sup> object rotating about an axle

The shaded piece, with mass  $dm$  has kinetic energy

$$dK = \frac{1}{2} dm v^2$$

where  $v$  is its speed. Now

$$v = \omega r.$$

Thus

$$dK = \frac{1}{2} dm r^2 \omega^2 = \frac{1}{2} r^2 dm \omega^2$$

Adding over all such contributions gives:

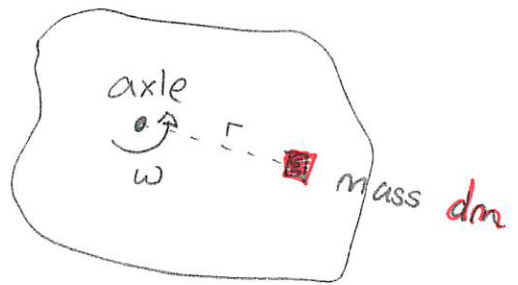
$$K = \int dK = \int \frac{1}{2} r^2 dm \omega^2$$

However  $\omega$  is constant. Thus

$$K = \frac{1}{2} \left[ \int r^2 dm \right] \omega^2$$

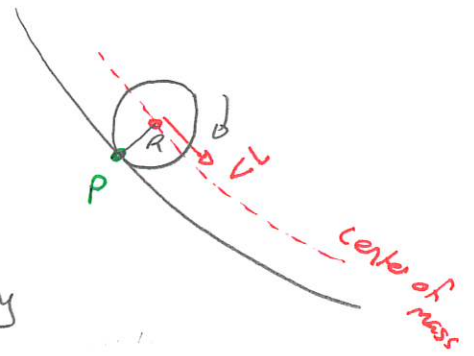
moment of inertia  $I$

$$\Rightarrow K = \frac{1}{2} I \omega^2 \quad \square$$



## Rotational and translational motion

Objects can simultaneously display rotational and translational motion. In this case they will have both translational and rotational kinetic energy. Let  $P$  be the point about which the object rotates. Let  $\vec{v}$  be the velocity of the center of mass. Then, we identify.



1) the translational kinetic energy (associated with the center-of-mass)

$$K_{\text{trans}} = \frac{1}{2} M v^2$$

total mass  $\nearrow$  speed of c.o.m.

2) the rotational kinetic energy

$$K_{\text{rot}} = \frac{1}{2} I \omega^2$$

moment of inertia about c.o.m.  $\nearrow$  angular velocity about  $P$

Then the total kinetic energy is

$$K = K_{\text{trans}} + K_{\text{rot}}$$

Then using Newton's 2<sup>nd</sup> + 3<sup>rd</sup> Law we can show that

If the net work done by non-conservative forces is zero then the energy

$$E = K + U_{\text{grav}} + U_{\text{spring}} + \dots$$

$$\hookrightarrow K_{\text{trans}} + K_{\text{rot}}$$

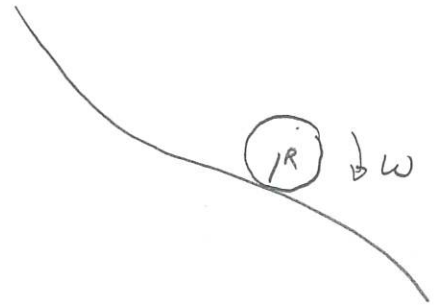
is constant (conserved)

## Rolling without slipping

We consider an object that rolls along a surface without slipping.

Suppose the object has a circular cross section with radius  $R$ . Then, if the object rolls without slipping, the speed of the center-of-mass satisfies

$$v = \omega R$$



We can incorporate this into the total kinetic energy

$$K = K_{\text{rot}} + K_{\text{trans}}$$

$$= \frac{1}{2} I \omega^2 + \frac{1}{2} M v^2$$

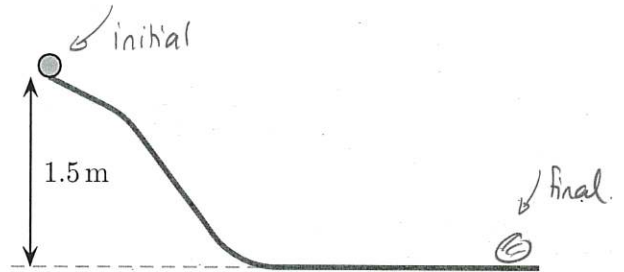
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substitute to relate  $v$  and  $\omega$  and remove one of these variables

### 324 Rolling cylinder

A cylinder with mass  $M$  and radius  $R$  is released from the top of a track with height 1.5 m. It rolls without slipping. Determine the speed of the cylinder at the bottom of the track. (131Sp2023)

rest at



Answer:  $E_f = E_i$

$$y_i = 1.5 \text{ m}$$

$$y_f = 0 \text{ m}$$

$$v_i = 0 \text{ m/s}$$

$$v_f = ?$$

$$\omega_i = 0 \text{ rad/s}$$

$$\omega_f = ?$$

$$K_{\text{trans}f} + K_{\text{rot}f} + U_{gf} = K_{\text{trans}i} + K_{\text{rot}i} + U_{gi}$$

$$\frac{1}{2} M v_f^2 + \frac{1}{2} I \omega_f^2 = M g y_i$$

For a cylinder  $I = \frac{1}{2} M R^2$ , Thus

$$\frac{1}{2} M v_f^2 + \frac{1}{2} \left( \frac{1}{2} M R^2 \right) \omega_f^2 = M g y_i$$

Now  $v_f = R \omega_f \Rightarrow \omega_f = v_f / R$ . Thus

$$\frac{1}{2} v_f^2 + \frac{1}{4} R^2 \frac{v_f^2}{R^2} = g y_i$$

$$\Rightarrow \frac{3}{4} v_f^2 = g y_i \Rightarrow v_f^2 = \frac{4 g y_i}{3}$$

$$\Rightarrow v_f = \sqrt{\frac{4 g y_i}{3}} = \sqrt{\frac{4 \times 9.8 \text{ m/s}^2 \times 1.5 \text{ m}}{3}}$$

$$= 4.4 \text{ m/s}$$

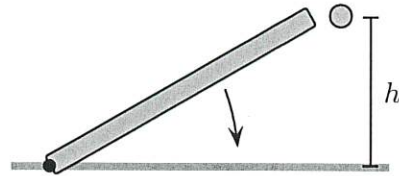
Quiz 2 30% - 60%  $\rightarrow$  30% - 70%

Quiz 3 20% - 10%  $\rightarrow$  0%

## Quiz 4

### 319 Toppling rod versus freely falling ball, 1

A rigid rod with uniformly distributed mass  $M$  and length  $L$  can pivot about a frictionless axle in a horizontal surface. The rod is held at rest with one end height  $h$  above the surface. A ball with mass  $m$  is also held at rest alongside the tip of the rod. Both are released at the same time. (131Sp2023)



- Determine the speed of the ball just before it hits the horizontal surface.
- Determine the speed of the tip of the rod just before it hits the horizontal surface.
- Which hits first?

Answer a)  $E_f = E_i$

$$K_f + U_{gf} = K_i + U_{gi} \Rightarrow \frac{1}{2} m v_f^2 + m g y_f = \frac{1}{2} m v_i^2 + m g y_i$$

$$\Rightarrow \frac{1}{2} m v_f^2 = m g h \Rightarrow v_f^2 = 2 g h$$

$$\Rightarrow v_f = \sqrt{2 g h}$$

b) Use the pivot as an axle

$$E_f = E_i$$

$$K_{rot f} + K_{trans f} + U_{gf} = K_{rot i} + K_{trans i} + U_{gi}$$

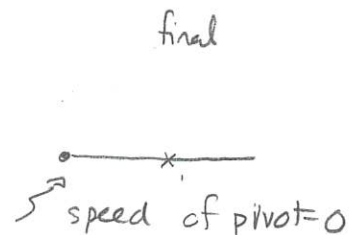
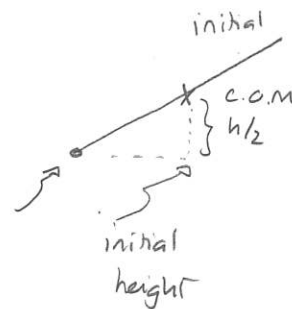
$$\frac{1}{2} I \omega_f^2 + \frac{1}{2} M v_f^2 = M g \frac{h}{2}$$

$$\frac{1}{2} \frac{1}{3} M L^2 \omega_f^2 = M g \frac{h}{2}$$

$$\Rightarrow \frac{1}{3} L^2 \omega_f^2 = g h$$

Now the speed of the tip is  $v_f = L \omega_f$

$$\Rightarrow \frac{1}{3} v_f^2 = g h \Rightarrow v_f = \sqrt{3 g h}$$



$$\Rightarrow \omega_f = \frac{v_f}{L}$$

$$I \text{ about end} = \frac{1}{3} M L^2$$