

Mon: HW Spm

Ex 227, 229, 232, 237, 238, 240, 242, 245

Tues: Warm Up (D2L)

Energy conservation

So far we have a system of energy conservation for situations involving gravity and springs

If gravity and springs are the only forces that do non-zero work on a system then the mechanical energy

$$E = K + U_{\text{grav}} + U_{\text{spring 1}} + U_{\text{spring 2}}$$

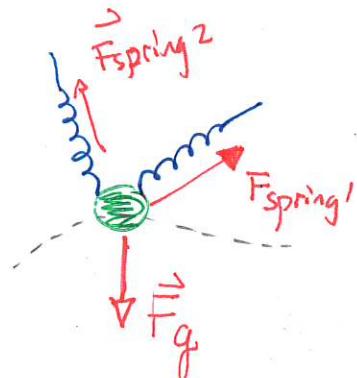
is constant throughout the motion of the system

Here

$$K = \frac{1}{2} M V^2$$

$$U_{\text{grav}} = m g y$$

$$U_{\text{spring}} = \frac{1}{2} k x^2$$



Quiz 1 70% - 90% { 90%

In the previous energy conservation rule, the potential energies completely account for the work done by the associated forces. Is this always possible?

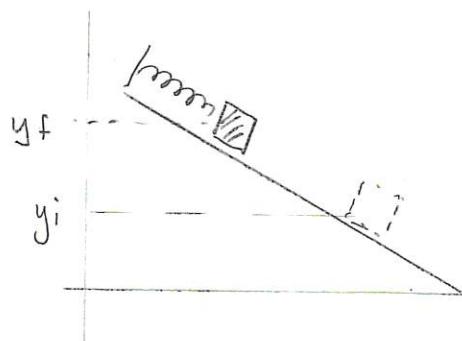
tension force \rightarrow work done by tension \neq some type of tension energy?

friction " \rightarrow " " friction \neq some type of friction energy?

Conservative forces

Recall that for gravity

$$W_{\text{grav}} = -mg y_f + mg y_i \\ = -U_{g f} + U_{g i} = -\Delta U_g$$



Similarly for a spring

$$W_{\text{spring}} = -\Delta U_{\text{spring}}$$

These are two examples of

$$W_{\text{force}} = -\Delta U_{\text{force}}$$

where U_{force} is the potential energy associated with the particular force. This potential energy only depends on the state of the system. For the two forces considered so far

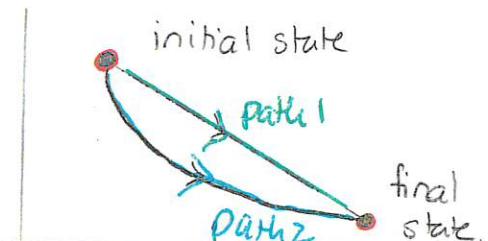
Force	Potential U_{force}	Depends on state via
gravity	$U_g = mg y$	mass of object, vertical position
spring	$U_{\text{spring}} = \frac{1}{2} kx^2$	spring constant, spring stretch/compression

↳ these don't depend on how the object moves / changes position.

This has an important implication

for the work done. Consider an object starting in an initial state and making its way to a final state via one of two possible paths. Then

$$W_{\text{grav}} (\text{path 1}) = W_{\text{grav}} (\text{path 2})$$



since the work done by gravity only depends on the initial and final states.

This can be extended to any paths:

The work done by gravity between an initial location (state) and final location (state) does not depend on the path between those locations.

These are examples of conservative forces.

A force is called
conservative,



The work done by the force only depends on the initial and final configuration/state of the system and not the trajectory between these.



Connection via calculus
in three dimensions

There exists a potential energy U_{force} , that only depends on the state of the system such that the work done by the force is

$$W_{\text{force}} = -\Delta U_{\text{force}}$$

Thus we already have two examples of conservative forces:

- 1) gravity (near Earth's surface)
- 2) spring force

Is this true for any force?

Quiz 2 70% - 100% \nexists 50% - 70%

Quiz 3 30% \nexists 40% - 50%

We see that because work done depends on the path taken:

Friction is non-conservative

Other examples of non-conservative forces are:

- 1) tension
- 2) normal force

So there is no possible potential energy for:

- 1) friction
- 2) tension
- 3) normal force..

Mechanical energy in general

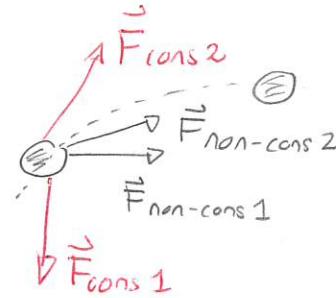
Can we still use $E = K + U_{\text{grav}} + \dots$ if there are non-conservative forces that do work? We can by dividing the forces into conservative and non-conservative.

Then

$$\Delta K = W_{\text{net}}$$

$$= W_{\text{cons}1} + W_{\text{cons}2} + \dots$$

$$+ W_{\text{non-cons}1} + W_{\text{non-cons}2} + \dots$$



Then for conservative forces there is a potential s.t. $W_{\text{cons}j} = -\Delta U_{\text{cons}j}$. So

$$\Delta K = -\Delta U_{\text{cons}1} - \Delta U_{\text{cons}2} - \Delta U_{\text{cons}3} \dots + W_{\text{non-cons}1} + \dots$$

$$\Rightarrow \Delta K + \Delta U_{\text{cons}1} + \Delta U_{\text{cons}2} + \dots = W_{\text{non-cons}1} + W_{\text{non-cons}2} + \dots$$

So we define the total energy as

$$E = K + U_{\text{cons}1} + U_{\text{cons}2} + \dots$$

and the total work done by all non-conservative forces:

$$W_{\text{nc}} = W_{\text{non-cons}1} + W_{\text{non-cons}2} + \dots$$

This gives

$$\Delta E = W_{\text{nc}}$$

248 Spring, cart and hand

A 5.0 kg cart can slide along a frictionless horizontal surface. A spring, with spring constant 400 N/m connects the cart to a wall. The spring is initially compressed by 0.25 m and the cart is held at rest. It is released and subsequently a hand pushes with a constant 30 N force against the spring as the spring relaxes. Determine the speed of the cart when the spring reaches its equilibrium position. (131Sp2023)



Ans: Initial: spring released

$$v_i = 0 \text{ m/s} \quad v_f = ?$$

Final: at equilibrium

$$x_i = 0.25 \text{ m} \quad x_f = 0$$

$$\Delta E = W_{nc}$$

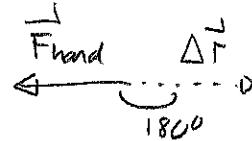
$$y_i = 0 \quad y_f = 0$$

where

$$E = K + U_{grav} + U_{spring}$$

$$W_{nc} = W_{hand}$$

$$\begin{aligned} \text{Then } W_{hand} &= F_{hand} \Delta r \cos \theta \\ &= 30 \text{ N} \times 0.25 \text{ m} \cos 180^\circ \\ &= -7.5 \text{ J} \end{aligned}$$



$$\text{Now } \Delta E = W_{nc}$$

$$\Rightarrow E_f - E_i = W_{hand}$$

$$\Rightarrow E_f = E_i + W_{hand}$$

$$K_f + U_{gf} + U_{spf} = K_i + U_{gi} + U_{spi} + W_{hand}$$

$$\frac{1}{2} M V_f^2 + M g y_f + \cancel{\frac{1}{2} k x_f^2} = \cancel{\frac{1}{2} M V_i^2} + M g y_i + \frac{1}{2} k x_i^2 - 7.5 \text{ J}$$

$$\frac{1}{2} M V_f^2 = \frac{1}{2} k x_i^2 - 7.5 \text{ J}$$

$$\frac{1}{2} 5.0 \text{ kg } V_f^2 = \frac{1}{2} 400 \text{ N/m } (0.25 \text{ m})^2 - 7.5 \text{ J}$$

∴

$$\Rightarrow 2.5 \text{ kg } V_f^2 = 12.5 \text{ J} - 7.5 \text{ J} \Rightarrow V_f^2 = \frac{5.0 \text{ J}}{2.5 \text{ kg}} = 2 \text{ m}^2/\text{s}^2 \Rightarrow V_f = 1.4 \text{ m/s}$$