

Tues: HW by 5pm

Weds: Read. 7.5, 7.6

Wavefunctions in spherical co-ordinates

A wavefunction in spherical co-ordinates can be used to determine probabilities of position measurement outcomes via

$$\begin{aligned} \text{Prob } [r_0 \leq r \leq r_1, \text{ AND } \theta_0 \leq \theta \leq \theta_1, \text{ AND } \phi_0 \leq \phi \leq \phi_1] \\ = \int_{r_0}^{r_1} \int_{\theta_0}^{\theta_1} \int_{\phi_0}^{\phi_1} |\Psi(r, \theta, \phi)|^2 r^2 \sin \theta \, dr \, d\theta \, d\phi \end{aligned}$$

Example: The wavefunction

$$\Psi(r, \theta, \phi) = \frac{1}{\sqrt{\pi a^3}} e^{-r/a} e^{2i\phi}$$

is normalized. Determine the probability with which a position measurement outcome gives $r > a$ regardless of θ and ϕ .

$$\begin{aligned} \text{Answer: Prob } (r > a) &= \int_a^\infty \int_0^\pi \int_0^{2\pi} \frac{1}{\pi a^3} e^{-2r/a} r^2 \sin \theta \, dr \, d\theta \, d\phi \\ &= \frac{1}{\pi a^3} \int_a^\infty r^2 e^{-2r/a} \, dr \underbrace{\int_0^\pi \sin \theta \, d\theta}_2 \underbrace{\int_0^{2\pi} d\phi}_{2\pi} \end{aligned}$$

$$\Rightarrow \text{Prob}(r > a) = \frac{1}{\pi a^3} \int_a^{\infty} e^{-2r/a} r^2 dr \quad 4\pi$$

$$= \frac{4}{a^3} \left[\frac{5a^3 e^{-2}}{4} \right] = 5e^{-2} = 0.68 \quad \square$$

Schrödinger equation in spherical co-ordinates

The TISE for the hydrogen atom is:

$$-\frac{\hbar^2}{2m_e} \left[\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right] - \frac{1}{4\pi\epsilon_0} \frac{e^2}{r} \psi = E \psi$$

↖ mass of electron

We need to convert the derivatives into spherical co-ordinates. Note that

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \neq \frac{\partial^2 \psi}{\partial r^2} + \frac{\partial^2 \psi}{\partial \theta^2} + \frac{\partial^2 \psi}{\partial \phi^2}$$

To see this:

$$\frac{\partial \psi}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial \psi}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial \psi}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial \psi}{\partial \phi}$$

$$\text{Then } r = \sqrt{x^2 + y^2 + z^2} \Rightarrow \frac{\partial r}{\partial x} = \frac{x}{r} = \sin\theta \cos\phi$$

$$\theta = \tan^{-1}\left(\frac{z}{\sqrt{x^2 + y^2}}\right) \Rightarrow \frac{\partial \theta}{\partial x} = \frac{\cos\theta \sin\phi}{r}$$

gives:

$$\frac{\partial \psi}{\partial x} = \sin\theta \cos\phi \frac{\partial \psi}{\partial r} + \frac{\cos\theta \sin\phi}{r} \frac{\partial \psi}{\partial \theta} + \dots$$

This gets more complicated when we take second derivatives.

A derivation eventually gives:

$$\nabla^2 \Psi = \frac{1}{r^2} \left[\frac{\partial}{\partial r} \left(r^2 \frac{\partial \Psi}{\partial r} \right) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Psi}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 \Psi}{\partial \phi^2} \right]$$

Then the TISE for the hydrogen atom in spherical co-ordinates is

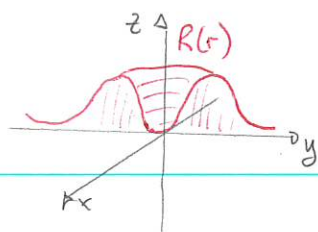
$$-\frac{\hbar^2}{2m_e} \frac{1}{r^2} \left[\frac{\partial}{\partial r} \left(r^2 \frac{\partial \Psi}{\partial r} \right) + \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \Psi}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2 \Psi}{\partial \phi^2} \right] - \frac{1}{4\pi\epsilon_0} \frac{e^2}{r} \Psi(r, \theta, \phi) = E \Psi(r, \theta, \phi)$$

Separation of variables for the hydrogen atom

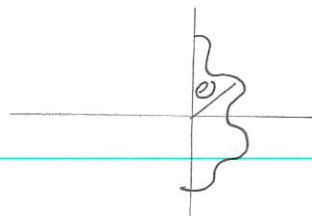
We solve the TISE by separating variables. Try

$$\Psi(r, \theta, \phi) = \underbrace{R(r)}_{\text{radial part}} \underbrace{\Theta(\theta)}_{\text{Polar part}} \underbrace{\Phi(\phi)}_{\text{azimuthal part}}$$

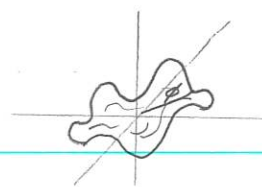
radial part



Polar part



azimuthal part



The mathematical steps for doing this are described on pg 247 The results are:

Azimuthal part: $\frac{d^2 \Phi}{d\phi^2} = -D \Phi$

where D is a constant

Polar part

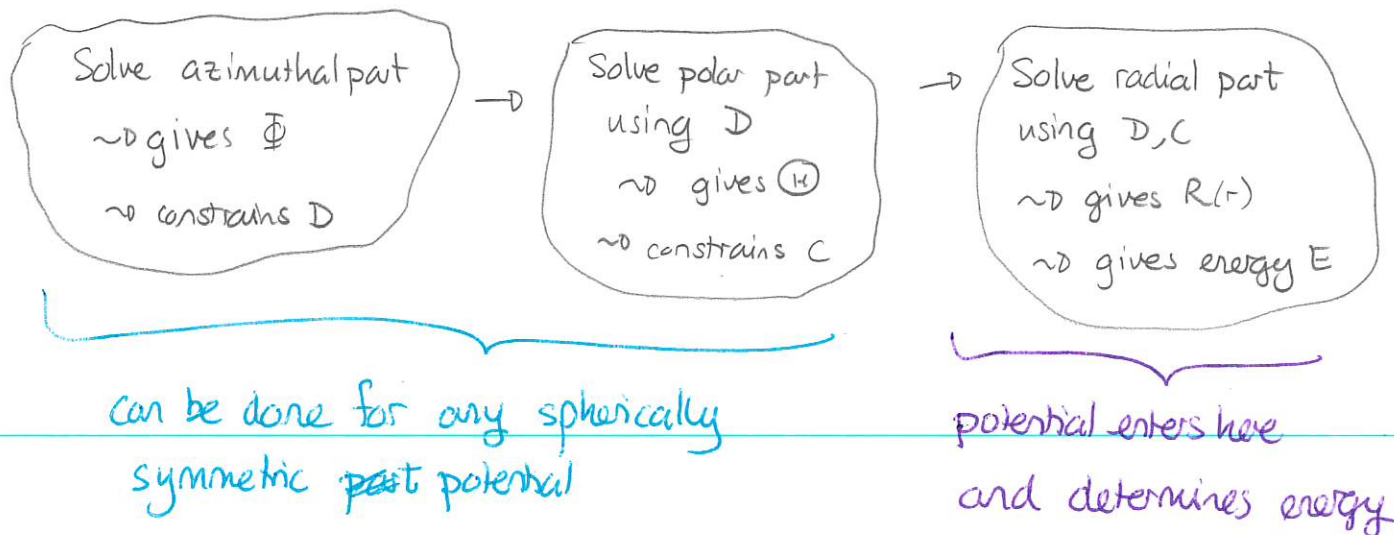
$$\sin\theta \frac{d}{d\theta} \left(\sin\theta \frac{d\Theta}{d\theta} \right) - C(\sin^2\theta)\Theta = 0$$

where C is a constant.

Radial part

$$-\frac{d}{dr} \left(r^2 \frac{dR}{dr} \right) - \frac{2m_e r^2}{\hbar^2} E R(r) + \frac{2m_e r^2}{\hbar^2} \underbrace{U(r)}_{-\frac{1}{4\pi\epsilon_0} \frac{e^2}{r}} R(r) = C R(r)$$

The general strategy is:



Azimuthal part

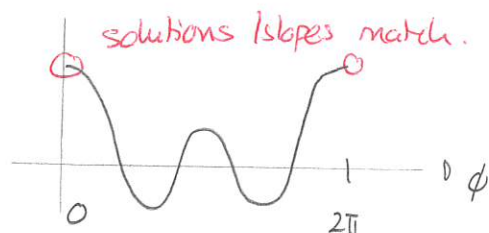
The azimuthal equation give $\Phi(\phi)$ via

$$\frac{d^2 \Phi}{d\phi^2} = -D \Phi$$

and is constrain by the fact that Φ must be continuous. So at $\phi=0$ and 2π the wavefunction must give the same results. Thus

$$* \quad \Phi(2\pi) = \Phi(0)$$

$$* \quad \left. \frac{d\Phi}{d\phi} \right|_{2\pi} = \left. \frac{d\Phi}{d\phi} \right|_0$$



There are two possibilities. First, if $D < 0$ we get

$$\Phi(\phi) = A e^{\sqrt{-D} \phi} + B e^{-\sqrt{-D} \phi}$$

$$\text{Then } \Phi(0) = \Phi(2\pi) \Rightarrow A + B = A e^{\sqrt{-D} 2\pi} + B e^{-\sqrt{-D} 2\pi}$$

$$\Phi'(0) = \Phi'(2\pi) \Rightarrow A - B = A e^{\sqrt{-D} 2\pi} - B e^{-\sqrt{-D} 2\pi}$$

$$\text{adding gives } A = A e^{\sqrt{-D} 2\pi} \Rightarrow D = 0$$

$$B = B e^{-\sqrt{-D} 2\pi} \Rightarrow D = 0$$

Second consider $D > 0$. Then possible solutions are:

$$\Phi = e^{\pm i\sqrt{D} \phi}$$

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We see that we need $\sqrt{D} = \text{integer} = m\ell = 0, \pm 1, \pm 2, \dots$. Then

$$\Phi(\phi) = e^{im\ell \phi}$$

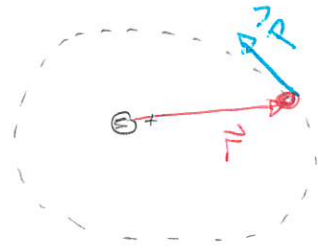
$$\text{where } m\ell = 0, \pm 1, \pm 2, \dots \quad \text{and } D = m\ell^2$$

We can interpret these solutions in terms of angular momentum. In classical physics the angular momentum of a particle is

$$\vec{L} = \vec{r} \times \vec{p}$$

and this has component form

$$\vec{L} = L_x \hat{x} + L_y \hat{y} + L_z \hat{z}$$



In quantum theory there must be an angular momentum operator associated with each component:

$\hat{L}_x \sim$ angular momentum x component

$\hat{L}_y \sim$ " " y "

$\hat{L}_z \sim$ " " z "

We can show the following.

In spherical co-ordinates the z-component angular momentum is

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \phi}$$

and the expectation value of L_z for the states used here is

$$\langle L_z \rangle = \int \Psi^* \hat{L}_z \Psi dV = 0 \quad \langle L_z \rangle = m\hbar$$

and the uncertainty in L_z is $\sigma_z = 0$

Thus a solution with

$$\Phi(\phi) = e^{im\phi}$$

corresponds to a z-component of angular momentum exactly equal to $m\hbar$

$$\Rightarrow L_z = 0, \pm\hbar, \pm 2\hbar, \pm 3\hbar, \dots$$

Derivation First

$$\vec{L} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ x & y & z \\ p_x & p_y & p_z \end{vmatrix} = (yp_z - zp_y)\hat{x} + (zp_x - xp_z)\hat{y} + (xp_y - yp_x)\hat{z}$$

$$\Rightarrow L_z = xp_y - yp_x \quad \text{classically.}$$

The quantum operator is

$$\begin{aligned} \hat{L}_z &= \hat{x}\hat{p}_y - \hat{y}\hat{p}_x \\ &= x(-i\hbar\frac{\partial}{\partial y}) - y(-i\hbar\frac{\partial}{\partial x}) = -i\hbar \left[x\frac{\partial}{\partial y} - y\frac{\partial}{\partial x} \right] \end{aligned}$$

Then in spherical co-ords.

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \theta}{\partial x} \frac{\partial}{\partial \theta} + \frac{\partial \phi}{\partial x} \frac{\partial}{\partial \phi}$$

$$\frac{\partial r}{\partial x} = \cos\phi \sin\theta$$

$$\begin{aligned} \theta &= \tan^{-1}\left(\frac{z}{\sqrt{x^2+y^2}}\right) \Rightarrow \frac{\partial \theta}{\partial x} = \frac{1}{1+z^2/(x^2+y^2)} \cdot \frac{z}{(x^2+y^2)^{3/2}} \left(-\frac{1}{z}\right) 2x \\ &= -\frac{1}{r^2} \frac{r \cos\theta \cdot r \cos\phi \sin\theta}{r \sin\theta} \\ &= -\frac{1}{r} \cos\theta \cos\phi \end{aligned}$$

$$\begin{aligned} \phi &= \tan^{-1}\left(\frac{y}{x}\right) \Rightarrow \frac{\partial \phi}{\partial x} = \frac{1}{1+y^2/x^2} \left(-\frac{y}{x^2}\right) = \frac{-y}{x^2+y^2} = \frac{-r \sin\theta \sin\phi}{r^2 \sin^2\theta} \\ &= \frac{-\sin\phi}{r \sin\theta} \end{aligned}$$

Thus:

$$\frac{\partial}{\partial x} = \cos\phi \sin\theta \frac{\partial}{\partial r} - \frac{1}{r} \cos\theta \cos\phi \frac{\partial}{\partial \theta} - \frac{\sin\phi}{r \sin\theta} \frac{\partial}{\partial \phi}$$

Similarly

$$\frac{\partial}{\partial y} = \sin\phi \sin\theta \frac{\partial}{\partial r} - \frac{1}{r} \cos\theta \sin\phi \frac{\partial}{\partial \theta} + \frac{1}{r} \frac{\cos\phi}{\sin\theta} \frac{\partial}{\partial \phi}$$

So

$$\hat{L}_z = -i\hbar \left\{ r \cos\phi \sin\theta \left[\sin\phi \sin\theta \frac{\partial}{\partial r} - \frac{1}{r} \cos\theta \sin\phi \frac{\partial}{\partial \theta} + \frac{1}{r} \frac{\cos\phi}{\sin\theta} \frac{\partial}{\partial \phi} \right] - r \sin\phi \sin\theta \left[\cos\phi \sin\theta \frac{\partial}{\partial r} - \frac{1}{r} \cos\theta \cos\phi \frac{\partial}{\partial \theta} - \frac{1}{r} \frac{\sin\phi}{\sin\theta} \frac{\partial}{\partial \phi} \right] \right\}$$

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \phi}$$

The expectation value is

$$\begin{aligned} \langle L_z \rangle &= \int_0^\infty \int_0^\pi \int_0^{2\pi} \Psi^*(r, \theta, \phi) L_z \Psi(r, \theta, \phi) r^2 \sin\theta dr d\theta d\phi \\ &= \int_0^\infty \int_0^\pi \int_0^{2\pi} \Psi^* (-i\hbar) \frac{\partial \Psi}{\partial \phi} r^2 \sin\theta dr d\theta d\phi \end{aligned}$$

Then $\frac{\partial \Psi}{\partial \phi} = i m_l \Psi$ gives

$$\langle L_z \rangle = m_l \hbar \underbrace{\int_0^\infty \int_0^\pi \int_0^{2\pi} \Psi^* \Psi r^2 \sin\theta dr d\theta d\phi}_1 = m_l \hbar$$

Then we can show $\langle L_z^2 \rangle = m_l^2 \hbar^2 \Rightarrow \sigma_{L_z} = \sqrt{\langle L_z^2 \rangle - \langle L_z \rangle^2} = 0$