

Mon HW due

read: King Ch 1.2.4, 1.2.5, 1.3.1  $\rightarrow$  1.3.3

Exam: Average 70%

## Vibrations + Oscillations

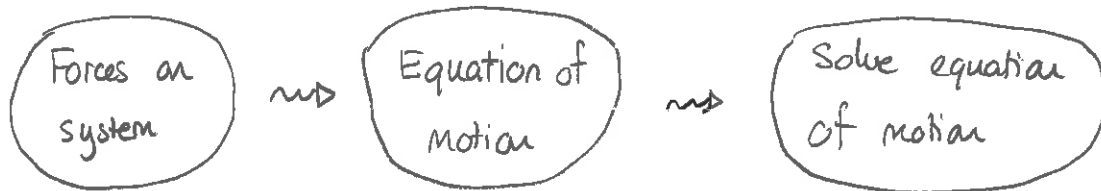
Consider a mass that is suspended from a spring. If the mass is pulled down and released, then it will subsequently repeatedly bounce up and down. Motion of this type in which a basic pattern is repeated over and over is called an oscillation. Examples of oscillations include:

- 1) mass/spring systems
- 2) pendulum
- 3) currents + voltages in circuits
- 4) vibrations in solids / crystal lattices
- 5) wave motion
- 6) quantum theory descriptions of light.

We shall consider examples of oscillations taken from classical physics. We aim to use Newtonian physics to describe these but will develop a language suitable for describing oscillatory phenomena.

## Mass and Spring

A classical example of an oscillating system is a mass attached to a spring. Suppose that the mass is supported by a horizontal frictionless surface. We can assess the situation using Newtonian mechanics. Schematically



We describe the system configuration via one variable

$$x = \text{displacement from equilibrium}$$

Ultimately we want to know how  $x$  depends on time.

Newtonian mechanics starts with

$$\vec{F}_{\text{net}} = m\vec{a}$$

For purely horizontal motion  $\vec{n} = -\vec{F}_G$  and  $\vec{F}_{\text{net}} = \vec{F}_{\text{spring}}$ . So

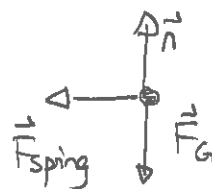
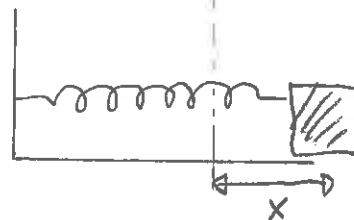
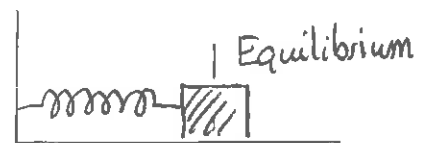
$$\vec{F}_{\text{spring}} = m\vec{a}$$

We only need to consider the horizontal component of motion. So

$$F_{\text{spring}x} = ma_x$$

But

$$a_x = \frac{dv_x}{dt} = \frac{d}{dt} \frac{dx}{dt} = \frac{d^2x}{dt^2}$$



Also by Hooke's Law

$$F_{\text{spring}} = -kx$$

where  $k$  is the spring constant. Substitution gives:

$$-kx = m \frac{d^2x}{dt^2}$$

which results in the equation of motion for the system

$$\boxed{\frac{d^2x}{dt^2} = -\frac{k}{m}x} \quad -(1)$$

The equation of motion is a differential equation with:

- 1) two constants  $k, m$  that do not depend on  $t$  but are determined by the actual physical system.
- 2) A function  $x = x(t)$  which depends on time

The equation of motion does not immediately yield the position as a function of time, but it does provide a rule that the position vs time function must satisfy.

Solving the equation of motion

What we really want is  $x = x(t)$ , that satisfies (1). Finding this is called "solving the equation of motion." In general solving the equation of motion means:

Find some function of time  $x = x(t)$  so that at any time  $t$ , both sides of (1) are satisfied.

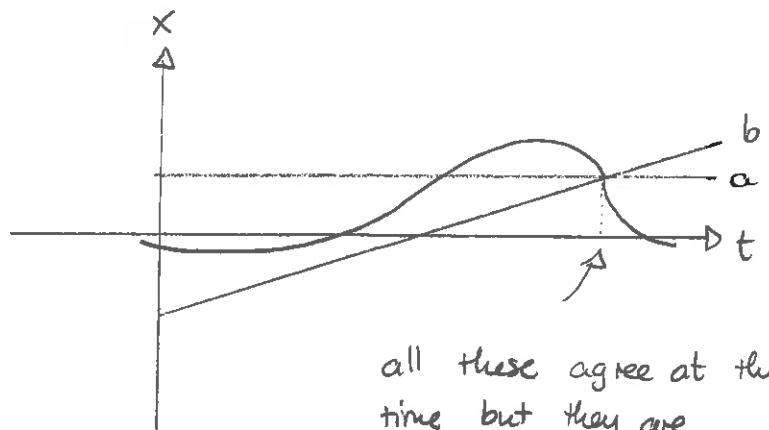
Quiz 1  $\frac{1}{7} \rightarrow \frac{4}{7}$

Quiz 2  $\frac{2}{7} \rightarrow \frac{7}{7}$

option 3 ambiguous  
does work at time  $t$ .

Note that we do not seek a solution that works for one particular time, but rather a solution that works for all times. We can represent this situation graphically. The issue becomes:

"Which graph satisfies (1) at all times?"



all these agree at this time but they are different functions.

Note that graphically

$$\frac{d^2x}{dt^2} > 0 \Rightarrow \text{concave up}$$

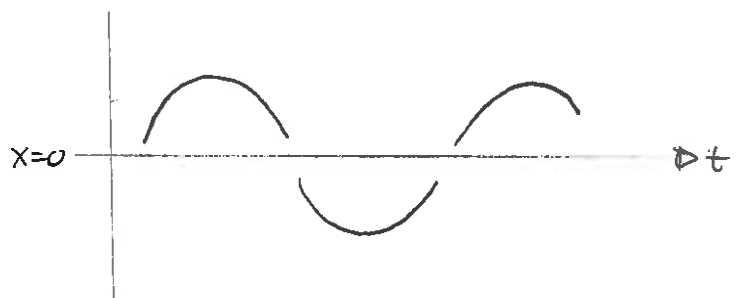
$$\frac{d^2x}{dt^2} < 0 \Rightarrow \text{concave down}$$

Noting that  $k/m > 0$  we have:

$$\text{If } x < 0 \text{ then } \frac{d^2x}{dt^2} > 0 \Rightarrow \text{concave up}$$

$$\text{If } x > 0 \text{ " } \frac{d^2x}{dt^2} < 0 \Rightarrow \text{concave down}$$

So the graph must have a form of the illustrated type.



There are formal mathematical methods for solving Eq.(1). But we can use graphical and physical insights to seek solutions. We guess the following:

$$x(t) \stackrel{??}{=} A \cos(\omega t).$$

where  $A$  and  $\omega$  do not depend on  $t$ .

Exercise: Show that  $x(t) = A \cos(\omega t)$  satisfies (i) provided that  $\omega$  satisfies a special condition. Find the condition.

Answer:  $\frac{dx}{dt} = -\omega A \sin(\omega t)$

$$\begin{aligned}\frac{d^2x}{dt^2} &= -\omega A \omega \cos(\omega t) = -\omega^2 A \cos(\omega t) \\ &= -\omega^2 x\end{aligned}$$

It works if and only if  $\omega^2 = k/m$   $\square$

So we have:

The equation of motion for the spring/mass system

$$\frac{d^2x}{dt^2} = -\frac{k}{m}x$$

has as a possible solution:

$$x = A \cos(\omega t)$$

where

$$\omega = \sqrt{\frac{k}{m}}$$

We can also see that for this solution:

$$\frac{d^2x}{dt^2} = -\omega^2 x$$

which is the equation of motion for a simple harmonic oscillator. The units of  $\omega$  are  $s^{-1}$ . To check

$$\left. \begin{array}{l} k \rightsquigarrow N/m = kg \cdot m/s^2/m = kg/s^2 \\ m \rightsquigarrow kg \end{array} \right\} \Rightarrow \omega \rightsquigarrow \sqrt{1/s^2} = s^{-1}$$

## Properties of the solution

A graph of  $x = A \cos(\omega t)$  indicates repeated motion

### Slide 1

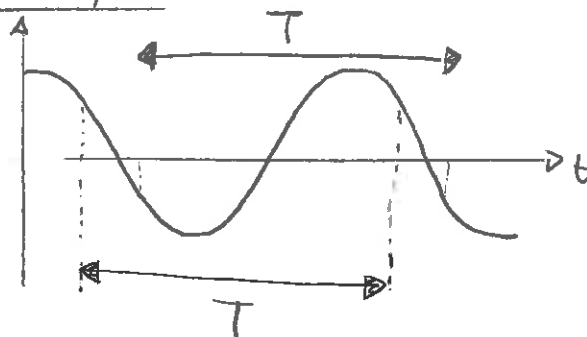
Note that this repeats at regular intervals. The period of oscillation is the shortest interval at which the pattern repeats.

This is denoted  $T$ . We can extract this mathematically by noting that

$$\cos(\omega t) = \cos(\omega t + n2\pi)$$

for any integer  $n$ . So

$$\cos(\omega t) = \cos\left(\omega\left(t + \frac{n2\pi}{\omega}\right)\right)$$



The pattern repeats at intervals spaced by times  $\frac{n2\pi}{\omega}$  apart. The shortest occurs when  $n=1$ . So

$$T = \frac{2\pi}{\omega}$$

The frequency of oscillation is

$$f = \frac{1}{T}$$

and is the number of complete cycles of oscillation per second. This has units  $s^{-1} \equiv \text{Hertz (Hz)}$ . It follows that

$$\omega = 2\pi f$$

and this is called the angular frequency.

Exercise: Determine the time taken to complete  $N$  cycles, in terms of frequency.

Answer: For one cycle time =  $T$ .

$$N \text{ " s time} = NT = N/f \equiv \Delta t$$

Thus  $f = \frac{N}{\Delta t}$ . If  $\Delta t = 1\text{s}$  and  $N = \text{number of cycles in 1 second}$ , then  $f = N$  cycles in one second.

The quantity  $A$  is called the amplitude of oscillation and is the maximum displacement from equilibrium.

### Quiz 3

Here  $v(t) = \frac{dx}{dt} = -\omega A \sin(\omega t)$ .

and  $a(t) = \frac{dv}{dt} = -\omega^2 A \cos(\omega t)$